From operations to neural network

Principles of object-oriented programming & neural networks

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Learning goals

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- apply object-oriented programming principles to implement a neural network
- understand the components of a neural network

Fundamentals

income (\$)	house-age (years)		house-value (\$)
83252	41		452600
83014	21		358500
	•••	•••	

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Goal learn weights w_1, w_2, \dots such that:

$$\begin{split} & w_1 \cdot 83252 + w_2 \cdot 41 + \ldots \approx 452600 \\ & w_1 \cdot 83014 + w_2 \cdot 21 + \ldots \approx 358500 \end{split}$$



Figure 1: a neural network with a single hidden layer



Implementation

Goal: Implementation using object-oriented programming (OOP) Class ideas? Goal: Implementation using object-oriented programming (OOP)

Class ideas?





Figure 3: Implementation example

Code

•••

Questions to ponder 🤔

- 1. Does it make sense to inherit Loss from Operation?
- 2. What happens if we use no activation function (a linear activation)? Try with single and many layers.
- 3. What happens if we take the the sum of the errors as a loss function?
- 4. What happens if we don't standardize the features before we use them for training?
- 5. What happens if we choose a learning rate of 1?

Takeaways

- breakpoint() is useful for debugging while interacting with the program in ipython
- many bugs through Numpy broadcasting, etc scalar multiplying a (3, 1) array with a (3,) array. Assertions help.



Code 2019, Weidman, Deep Learning from Scratch there are occasional mistakes in the book refer to

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German version

Appendix

 $\begin{array}{ccc} x & y \\ 1 & 2 \\ 2 & 4 \\ 3 & 6 \\ 4 & ? \\ -1 & ? \end{array}$

x	y
1	1.99
2	4.02
3	5.98
4	?
-1	?

x_1	x_2	y
1	1	1.5
2	1	2.5
2	2	3
3	1	?
-1	2	?

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We can compare each prediction p_i (using $w_i \mathbf{s}$) with the actual house value $(y_i).$

? How do we test the prediction quality using math?

- **?** How do we test the prediction quality using math?
- For example by using *mean squared error* (MSE).

$$\frac{(y_1-p_1)^2+(y_2-p_2)^2+\ldots+(y_n-p_n)^2}{n}$$

MSE is - a loss function - measures how erroneous the prediction is



Figure 4: Alternative view to components

Linear vs non-linear activation



Goal: minimum loss by training:

- Pick random parameters (weights)
- Make predictions for a batch of inputs
- Compute loss
- Find the parameters (weights) that minimize the loss
- **?** How can we find these parameters?

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! Taking the partial derivative with respect to each parameter (*gradient*). However we typically cannot find the exact minimum, because the loss function can get very complex.

? What do we do now?

Alternative perspective follows:



? You are stuck on a mountain. How would you get down?

Approach: Find out how much we should change each parameter so that the loss decreases.

? How can we find out how much the loss L changes if we e.g., increase the parameter w_1 by 1?

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? How can we find out how much the loss L changes if we e.g., increase the parameter w_1 by 1?

By computing $\frac{\partial L}{\partial w_1}(w_1 = 1)$. If the result is positive, then we decrease w_1 and vice-versa. This is called *back-propagation*.



Gradient descent II

Procedure: Pick a random point, move in direction of the descending path:



Revised algorithm

Goal: minimum loss by training:

- Pick random parameters (weights)
- Repeat:
 - Make predictions for a batch of inputs
 - Compute loss
 - Back-propagate
 - Modify the parameters so that the loss decreases a bit
 - Stop if the loss does not decrease significantly or after a timeout ##



Figure 5: Implementation example with methods



Figure 6: Implementation example with every component

Why OOP?

- encapsulation of features in a single component more convenient for humans to classify components of a program
 - reusability of components, extensibility